




1 NumbaCS: A fast Python package for coherent 2 structure analysis

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6 Summary

7 NumbaCS (Numba Coherent Structures) is a Python package that implements a variety of
8 coherent structure methods in an efficient and user-friendly manner. “Coherent structure
9 methods” refer to any method which can be used to infer or extract Lagrangian and objective
10 Eulerian coherent structures. The theory behind these methods have been developed over
11 the last few decades with the aim of extending many of the important invariant objects from
12 time-independent dynamical systems theory to the more general setting where a system may
13 have arbitrary time dependence and may only be known or defined for some finite time. These
14 time-dependent systems are ubiquitous in the context of geophysical and engineering flows
15 where the evolution of the velocity field depends on time and velocity data representing these
16 flows is not available for all time. By extending the ideas from the time-independent setting to
17 the more general time-dependent setting, important transient objects (coherent structures) can
18 be identified which govern how material is transported within a flow. Understanding material
19 transport in flows is of great importance for applications ranging from monitoring the transport
20 of a contaminant in the ocean or atmosphere to informing search and rescue strategies for
21 persons lost at sea.

22 Statement of need

23 As theory and implementations of coherent structures have been developed ([Farazmand &
24 Haller, 2012](#); [Haller, 2011](#); [Haller et al., 2016](#); [Haller & Beron-Vera, 2013](#); [Haller & Poje,
25 1998](#); [Mathur et al., 2007](#); [Nolan, Serra, et al., 2020](#); [Schindler et al., 2012](#); [Serra & Haller,
26 2016](#); [Shadden et al., 2005](#)) and the utility of these tools has been demonstrated over the last
27 two decades ([Curbelo & Rypina, 2023](#); [Du Toit & Marsden, 2010](#); [Günther et al., 2021](#); [Liu
28 et al., 2018](#); [Nolan, Foroutan, et al., 2020](#); [Peacock & Haller, 2013](#); [Pretorius et al., 2023](#);
29 [Rutherford et al., 2012](#); [Serra et al., 2017](#)), there has been a steadily growing interest in using
30 these methods for real-world applications. Early on, software implementations were largely
31 contained to in-house packages developed by applied mathematicians and engineers advancing
32 the theory. Over the years, there have been a number of software packages developed in an
33 attempt to provide implementations of some of these methods for practitioners outside of the
34 field. Some provide a friendly interface for users ([Dynlab – Nolan \(2024\)](#); [LCS MATLAB Kit –
35 Dabiri \(2009\)](#)), others aim to provide efficient implementations of specific methods (sometimes
36 in specific circumstances) ([Lagrangian – Briol & d’Ovidio \(2011\)](#); [Newman – Du Toit \(2010\)](#);
37 [Aquila-LCS – Lagares & Araya \(2023\)](#)), and a few implement a variety of methods ([Tbarrier
38 – Bartos et al. \(2022\)](#); [LCS Tool - Onu et al. \(2015\)](#)). NumbaCS intends to unite these
39 aims by providing efficient and user-friendly implementations of a variety of coherent structure
40 methods. By doing this, the hope is to provide a powerful tool for experienced practitioners
41 and a low barrier of entry for newcomers. In addition, as new methods/implementations arise,
42 the framework laid out in NumbaCS provides a straightforward environment for contributions

43 and maintenance. Also of note is another package called `CoherentStructures.jl` (Junge et
44 al., 2020), which is fast, user-friendly, and implements a variety of methods. This package
45 has some overlap with `NumbaCS` but they both implement methods which the other does not.
46 `CoherentStructures.jl` is a powerful tool that should be considered by users who perhaps
47 prefer Julia to Python or are interested in computing some of the methods not implemented in
48 `NumbaCS`. For a more detailed breakdown of how all of the mentioned packages compare with
49 `NumbaCS`, see the [documentation](#).

50 Functionality

51 `NumbaCS` implements the following features for both analytical and numerical flows:

- 52 ■ Standard flow map computation
- 53 ■ Flow map composition method (Brunton & Rowley, 2010)
- 54 ■ Finite time Lyapunov exponent (FTLE) (Shadden et al., 2005)
- 55 ■ instantaneous Lyapunov exponent (iLE) (Nolan, Serra, et al., 2020)
- 56 ■ Lagrangian averaged vorticity deviation (LAVD) (Haller et al., 2016)
- 57 ■ Instantaneous vorticity deviation (IVD) (Haller et al., 2016)
- 58 ■ FTLE ridge extraction (Schindler et al., 2012; Steger, 1998)
- 59 ■ Variational hyperbolic LCS (Farazmand & Haller, 2012; Haller, 2011)
- 60 ■ Variational hyperbolic OECS (Serra & Haller, 2016)
- 61 ■ LAVD-based elliptic LCS (Haller et al., 2016)
- 62 ■ IVD-based elliptic OECS (Haller et al., 2016)

63 For flows defined by numerical velocity data:

- 64 ■ Simple creation of JIT compiled linear and cubic interpolants

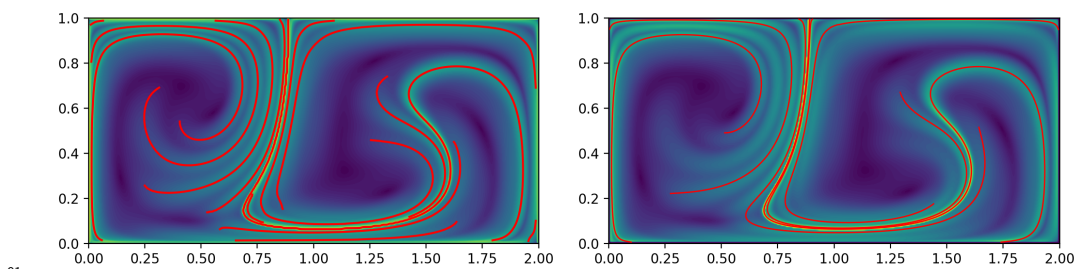
65 All of these implementations are relatively straightforward to use and quite efficient. This
66 is due to three key dependencies `NumbaCS` utilizes to speed up computations. The first is
67 `Numba` (Lam et al., 2015), a JIT compiler for Python which can drastically speed up numerical
68 operations and provides a simple framework for parallelizing tasks. Next, `numbaLSODA` (Wogan,
69 2021) is a Python wrapper to ODE solvers in both C++ (LSODA) and FORTRAN (DOP853)
70 that bypasses the Python interpreter and can be used within `Numba` functions (standard
71 Python ODE solvers cannot be executed within `Numba` functions). This package is crucial to
72 the efficiency of `NumbaCS` as particle integration is often the most costly part of finite-time
73 coherent structure methods. Finally, the `interpolation` package (Winant et al., 2017) provides
74 optimized interpolation in Python and is utilized in `NumbaCS` to create JIT compiled interpolant
75 functions, producing efficient implementations of methods even for flows defined by numerical
76 data. By taking advantage of these packages behind the scenes, `NumbaCS` is able to maintain
77 the simplicity and readability of an interpreted language while achieving runtimes closer to
78 that of a compiled language.

79 Examples

80 A [User Guide](#) is provided which details the workflow in `NumbaCS` and a number of examples
81 demonstrating the functionality are covered in the [Example Gallery](#). Here we show the output
82 of a few examples, provide the runtime of each, and breakdown the runtime based on the parts
83 of each method. “Flowmap” refers to the particle integration step, “C eig” and “S eig” refer
84 to the eigenvalue/vector step for Lagrangian and Eulerian methods respectively (this time will
85 be roughly equal to the FTLE and iLE times), and the last is the extraction time for a given
86 method. For examples that require particle integration, the default solver (DOP853) was used
87 with the default error tolerances (relative tolerance = $1e-6$, absolute tolerance = $1e-8$). All
88 runs were performed on an Intel^(R) CoreTM i7-3770K CPU @ 3.50GHz (which has 4 cores and

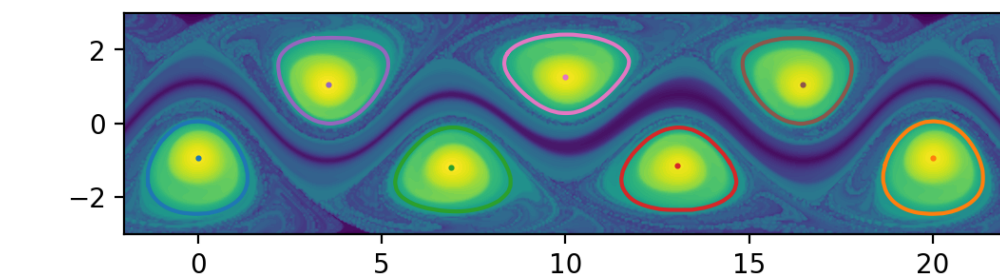
89 8 total threads). Warm-up time¹ is not included in the timings.

90 **Analytical Flow (Double Gyre)**



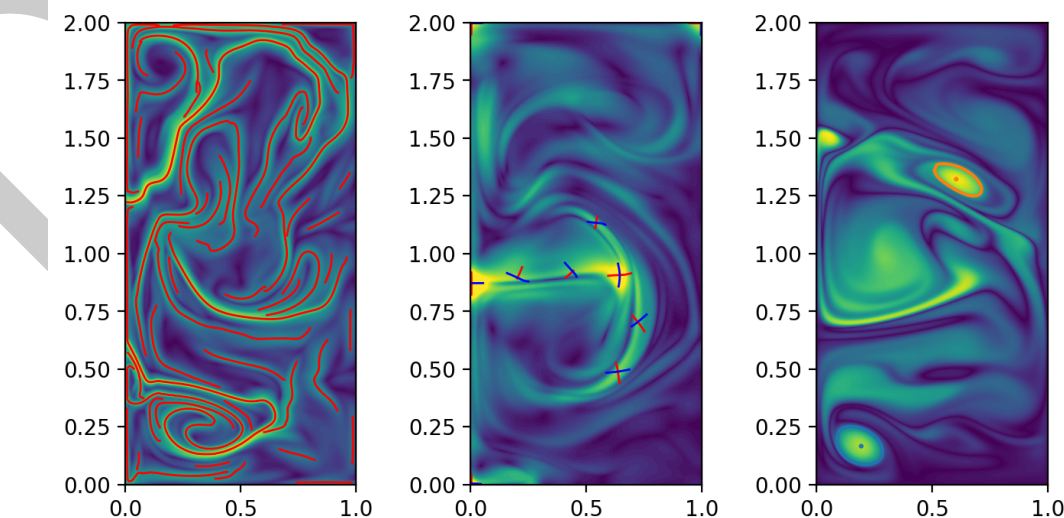
92 Left: **DG FTLE ridges** at $t_0 = 0$, integration time $T = -10$. Total runtime per iterate: ~ 0.424 s
 93 (flowmap: ~ 0.390 s; C eig: ~ 0.025 s; FTLE ridge extraction: ~ 0.009 s). Right: **DG hyperbolic**
 94 **LCS** at $t_0 = 0$, integration time $T = -10$. Total runtime per iterate: ~ 5.219 s (flowmap (aux
 95 grid): ~ 1.83 s; C eig (aux grid): ~ 0.039 s; hyperbolic LCS extraction: ~ 3.350 s). Both are
 96 computed over a 401×201 grid.

97 **Analytical Flow (Bickley jet)**



98
 99 **Bickley jet elliptic LCS** at $t_0 = 0$, integration time $T = 40$ days. Total runtime per iterate:
 100 ~ 9.200 s (flowmap: ~ 5.050 s; LAVD: ~ 4.140 s; elliptic LCS extraction: ~ 0.010 s). Computed over
 101 482×121 grid.

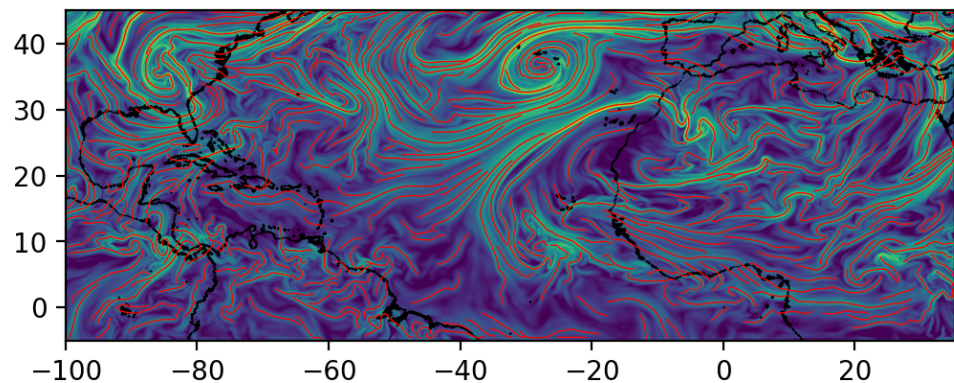
102 **Numerical Flow (QGE)**



103
¹Since many functions in NumbaCS are JIT compiled, these functions are optimized and compiled into machine code on the first function call. This initial delay is often referred to as "warm-up time". After the first call, subsequent function calls are much faster.

104 Left: [QGE FTLE ridges](#) at $t_0 = 0$, integration time $T = 0.1$. Total runtime per iterate:
105 ~ 2.461 s (flowmap: ~ 2.400 s; C eig: ~ 0.038 s; FTLE ridge extraction: ~ 0.023 s). Middle: [QGE](#)
106 [hyperbolic OECS](#) at $t_0 = 0.15$. Total runtime per iterate: ~ 2.238 s (S eig: ~ 0.038 s; hyperbolic
107 OECS extraction: ~ 2.200 s). Right: [QGE elliptic OECS](#) at $t_0 = 0.5$. Total runtime per iterate:
108 ~ 0.0452 s (IVD: ~ 0.0002 s; elliptic OECS extraction: ~ 0.045 s). All are computed over a 257×513
109 grid.

110 Numerical Flow (MERRA-2)



111
112 [MERRA-2 FTLE ridges](#) at $t_0 = 06/16/2020-00:00$, integration time $T = -72$ hrs. Total runtime
113 per iterate: ~ 7.835 s (flowmap: ~ 7.480 s; C eig: ~ 0.085 s; FTLE ridge extraction: ~ 0.27 s).
114 Computed over 902×335 grid.

115 Datasets

116 Two datasets are provided with NumbaCS to test the functionality for flows defined by numerical
117 velocity data. One is a numerical simulation of the quasi-geostrophic equations (QGE). We
118 thank the authors of Mou et al. (2021) for providing us with this dataset, which was used
119 extensively during development, and allowing a piece of the dataset to be included in the
120 package. The full dataset was over the time span $[10, 81]$ with $dt = 0.01$. We provide the
121 velocity fields over the much shorter time span of $[10, 11]$ with the same dt . For details on
122 parameters used in the simulation, refer to the cited paper. The other dataset is a MERRA-2
123 vertically averaged reanalysis dataset (Gelaro et al., 2017; GMAO, 2015), which was used as
124 part of a paper (Jarvis et al., 2024) coauthored by the authors of this paper. Wind velocity
125 fields were vertically averaged over pressure surfaces ranging from 500 hPa to 800 hPa. The
126 corresponding latitude, longitude, and date arrays are also provided. All data can be downloaded
127 from the [data folder](#) on the GitHub page.

128 Usage in ongoing research

129 As of the writing of this paper, NumbaCS has not been public for long but has been utilized
130 in one publication (Jarvis et al., 2024) where it was the computational tool for all coherent
131 structure methods. In addition, it is currently being used in an ongoing project focused on
132 airborne invasive species traveling from Australia to New Zealand titled "[Protecting Aotearoa](#)
133 [from wind-dispersed pests](#)". This is a five year (October 2023 - October 2028) Scion-led and
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